

COMP3630 / COMP6363

week 10: **Various**

Most is not based on the book

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Content of this Chapter

- On polytime-requirement for reductions
- Karp vs. Cook (reductions)
- Optimization problems

On polytime-requirement for reductions

On **P** membership vs. **P**-completeness

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- › However, we never did that for **P**... We only showed membership! Why?
 - Because we need a refined definition of **P**-hardness, because ...
 - otherwise, all problems in **P** are trivially **P**-hard and hence -complete!

P-completeness (Would-be)

Theorem w10.1

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- › Show that there exists a reduction r , such that for any $w \in \Sigma^*$, $w \in L'$ iff $r(w) \in L$.

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- › Define r as follows:
 - Let $w_{yes} \in L$ and $w_{no} \notin L$. These are constant and thus independent of any w .
 - Decide $w \in L'$ in polynomial time (possible by assumption).
 - If $w \in L'$, define $r(w) = w_{yes}$, otherwise $r(w) = w_{no}$. □

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- › A language L is called trivial iff $L = \emptyset$ or $L = \Sigma^*$.
- › In both cases, there does not exist both an w_{yes} instance and w_{no} instance.
- › So, no reduction is possible for trivial problems.

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- › The proof assumes that we “know” a constant $w_{yes} \in L'$ and $w_{no} \notin L'$. But do we?

 - One of them: yes, in polytime. Just take any word $w \in \Sigma^*$ and decide it in polytime. Then, either declare $w_{yes} := w$ (if $w \in L'$) or $w_{no} := w$ (if $w \notin L'$).
 - But how to find “the other answer”? Even if such a witness has polylength based on ... (what? the representation of the language?), there would still be exponentially many words to try.

This question relates to those “more philosophical ones” in the tutorial of week 9.

Why polytime reductions? Why not more?

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*Under poly-space reductions, all non-trivial problems in **PSPACE** are **PSPACE**-complete.*

Comment.

Recall that this includes all problems in **P** and **NP**.

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Proof.

Identical to the one before. Just replace **P** by **PSPACE** and poly-time by poly-space. \square

Karp vs. Cook (reductions)

Trivia

Stephen Cook

- › Formalized the notion of polytime-reductions in 1971, in his paper: “The Complexity of Theorem Proving Procedures”
- › Such reductions are also called “Cook-reductions” (see next slide)
- › Remember “Cook’s Theorem”? He proved SAT **NP**-complete.
- › He won the Turing Award (“Nobel Prize for Computer Science”) in 1982

Richard Karp

- › Proved 21 important problems **NP**-complete in his 1972 paper: “Reducibility Among Combinatorial Problems”
- › Provided an alternative definition of reductions, “Karp-reduction” (see next slide)
- › He won the Turing Award in 1985

Karp- and Cook-reductions

Definition w10.1 (Cook-reduction)

Let A and B be decision problems. We say that A Cook-reduces to B (written $A \leq_P^C B$) if there exists a deterministic Turing machine M that decides A in polynomial time with access to an oracle for B (arbitrarily often).

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Let A and B be decision problems. We say that A Karp-reduces to B (written $A \leq_P^K B$) if there exists a function $f : \Sigma^* \rightarrow \Sigma^*$ such that:

- f is computable in polynomial time, and
- for all $w \in \Sigma^*$: $w \in A$ if and only if $f(w) \in B$.

Note:

- > We use ...

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- > We use Karp-reductions!
- > Every Karp-reduction is also a Cook-reduction (trivially: the Cook oracle just calls the result of the Karp reduction).
- > Not every Cook-reduction is a Karp-reduction (non-trivial, skipped here).

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- › Every Karp-reduction is also a Cook-reduction (trivially: the Cook oracle just calls the result of the Karp reduction).
- › Not every Cook-reduction is a Karp-reduction (non-trivial, skipped here).
- › We get different theoretical results for those reductions (see next slide).

Karp vs. Cook reductions

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- › We don't know whether the set of **NP**-complete problems under Cook reductions are the same as those under Karp reductions.
- › If **P** = **NP** (note that the definition of **NP** does not depend on reductions), the two kinds of reductions are equally expressive.

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- › We have just considered yes/no problems
- › E.g., “Does problem P possess ‘a solution’?”

In Practice:

- › We want to *obtain* a solution! And maybe even the best!
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- › Yes/No problem: Does G have a vertex cover of size $\leq k$?
- › Optimization problem:
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Observation:

- › If we can solve the optimization problem, we can solve the yes/no problem.

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Optimisation Problems

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- › We know: yes/no version is **NP**-complete and $P \neq NP$ (as assumed).

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Return yes iff $s \leq k$.

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Return yes iff $s \leq k$.
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- › This is a contradiction to $\mathbf{P} \neq \mathbf{NP}$, so the optimization problem is not in **P**.



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Related to week 12:

(too complex, not covered)

Example w10.5

- › “Does the delete-relaxed HTN planning problem P have a solution?” can be expressed as a decision problem. (It is **NP**-complete, proved in 2014 by Alford et al.)
- › “Find a solution to the delete-relaxed HTN planning problem P .” is not a decision problem. Interestingly, even shortest solutions can be exponentially long in $|P|$! (Think of what that implies for certificates! How is that possible?!)