

Change the World – How Hard Can That Be? On the Complexity of Fixing Planning Models

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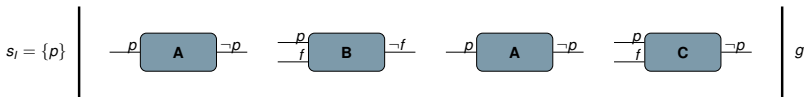
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Introduction

Motivation



An infeasible plan in which the action A deletes the fact p that is required by the actions A, B and C, and the environment does not have the fact f that is required by B and C as well.

- Counter-factual Explanations. (How to make the plan executable?)

	A	B	C
p	delete $\neg p$	N/A	N/A
	N/A	delete p	delete p
f	add f	N/A	N/A
	N/A	delete f	delete f

- Modeling assistance.

Scenario

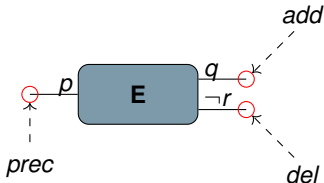
Given a plan that is supposed to be a solution to a planning problem, but it is actually not, we want to change the planning model so that it can be.

- Considering the problem in the context of hierarchical (HTN) & non-hierarchical planning.
- Complexity Study.

Changing Planning Models in Classical Planning

Basic Terminologies

- A state s is a set of proposition variables
- An action \mathbf{E} is a tuple $(prec, add, del)$
 - Preconditions $prec$: $prec \subseteq s$.
 - Effects add & del : $(s \setminus del) \cup add$.



An example of the action $\mathbf{E} = (\underbrace{\{p\}}_{prec}, \underbrace{\{q\}}_{add}, \underbrace{\{r\}}_{del})$.

Allowed Changes

Given an action sequence, we want to change actions' preconditions and effects to make the sequence executable.

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- FIX-ADD: Adding a variable to an action's add list.

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- FIX-PREC: Removing a variable from an action's precondition.
- FIX-ADD: Adding a variable to an action's add list.
- FIX-DEL: Removing a variable from an action's delete list.

Problem Definition: Definition

Definition (FIX-ACTION_X^k , $X \subseteq \{\text{PREC}, \text{ADD}, \text{DEL}\}$ and $|X| \geq 1$)

Given an action sequence \bar{a} , is there a way to make \bar{a} executable by using the respective changes according to the value of X at most k times.

- If $\text{PREC} \in X$, FIX-PREC is allowed.
- If $\text{ADD} \in X$, FIX-ADD is allowed.
- If $\text{DEL} \in X$, FIX-DEL is allowed.

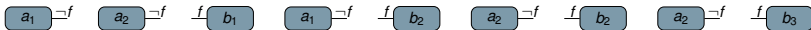
Results: FIX-PREC & FIX-DEL

Theorem

$\text{FIX-ACTION}_{\text{PREC,DEL}}$ is in P .

Proof.

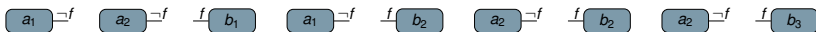
Reducing to the vertex cover problem with a bipartite graph as the input. □



An example of input action sequence in which $a_1 = a_2 = (\emptyset, \emptyset, \{f\})$ and $b_1 = b_2 = b_3 = (\{f\}, \emptyset, \emptyset)$.

*More complicated cases where $\text{prec} \cap \text{add} \cap \text{del} \neq \emptyset$ for some actions are considered in the proof presented in our paper.

Results: Reducing to the Vertex Covering Problem

 a_1 ● a_2 ●

Definition (Vertex Cover)

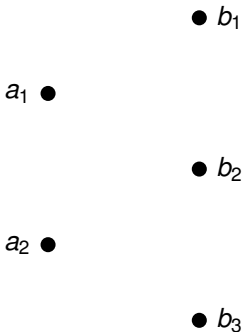
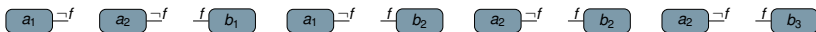
Given a graph, finding the minimum subset of the vertices such that for every edge, at least one of its endpoints is in the set.

The minimal vertex cover is

 $\{a_1, a_2\}. \implies$

The optimal change is removing f from the actions a_1 and a_2 .

Results: Reducing to the Vertex Covering Problem



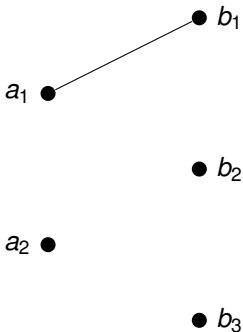
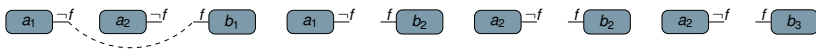
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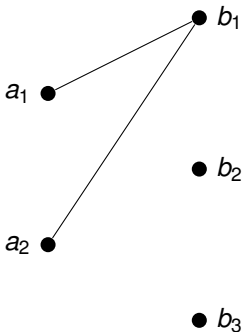
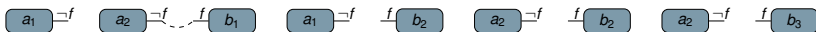
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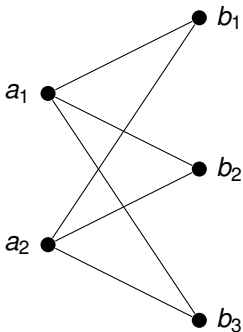
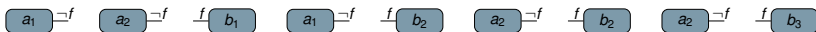
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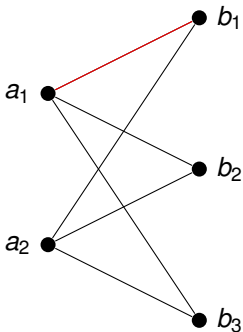
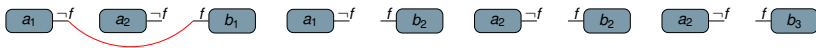
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Results: Only FIX-ADD

Theorem

$\text{FIX-ACTION}_{\text{ADD}}^k$ is NP-complete.

Proof.

Suppose the given action sequence is $\bar{a} = a_1 \cdots a_n$.

- Membership: Guessing at most $\min\{k, \sum_{i=1}^n |\text{prec}(a_i)|\}$ changes.
- Hardness: Reducing from the set covering problem.



Results: Set Covering

Definition

Given a set of sets $\mathcal{S} = \{S_1, \dots, S_n\}$ and an integer k , is there a subset S' of S such that $|S'| \leq k$ and $\bigcup_{S \in S'} S = \bigcup_{i=1}^n S_i$.

E.g., $\mathcal{S} = \{\underbrace{\{e_1\}}_{S_1}, \underbrace{\{e_1, e_2\}}_{S_2}, \underbrace{\{e_3\}}_{S_3}\}$ and $k = 2$.

- A solution to this instance is $S' = \{S_2, S_3\}$.

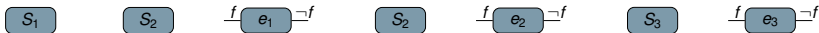
Results: Reduction from the Set Covering Problem



$$S_1 = \{e_1\}, S_2 = \{e_1, e_2\}, S_3 = \{e_3\}$$

- $e_i = (\{f\}, \emptyset, \{f\})$ ($1 \leq i \leq 3$)

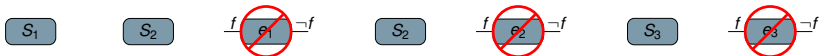
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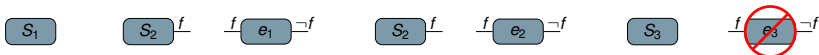
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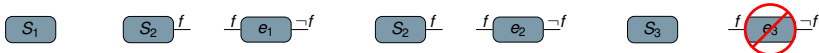
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Corollary

FIX-ACTION_X^k is NP-complete if $\text{ADD} \in X$.

Changing Planning Models in HTN Planning

HTN Planning: Components

- State s : A set of proposition variables.

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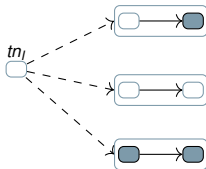
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- Methods - - → →

HTN Planning: Formalism

 tn_I
□ $P = (D, tn_I, s_I)$ with $D = (F, N_C, N_p, \delta, M)$

- F : A set of proposition variables called facts.
- N_C : A set of compound tasks.
- N_p : A set of primitive tasks (actions).
- $\delta: N_p \rightarrow 2^F \times 2^F \times 2^F$
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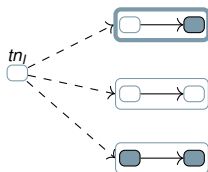


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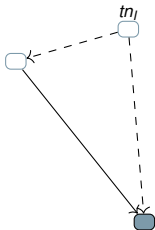


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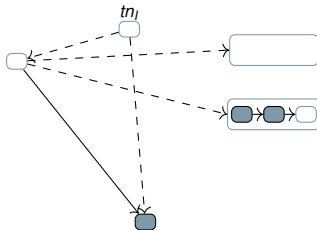


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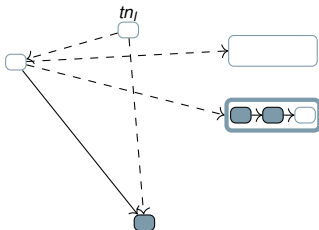


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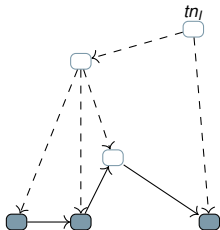


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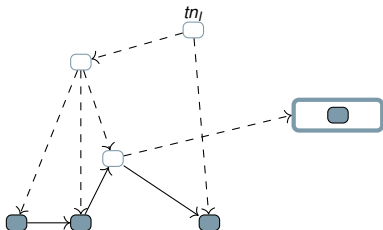


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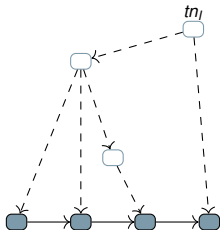


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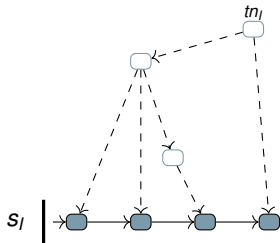


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- s_I : An initial state.

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Given an HTN planning problem and an action sequence, we want to change the planning model so that the given action sequence can be a solution.

- **ADD-ACTION:** Adding an action to a method.



- **DEL-ACTION:** Removing an action from a method.



Given Only an Action Sequence: Problem Definition

Definition (FIX-METHODS_X, $X \subseteq \{\text{ADD}, \text{DEL}\}$ and $|X| \geq 1$)

Given an HTN planning problem P and an action sequence tn , is there a way to change the methods in P by applying the respective changes according to the value of X so that tn becomes a solution.

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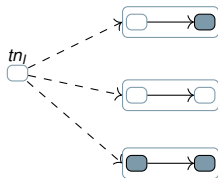
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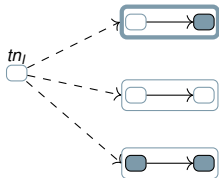
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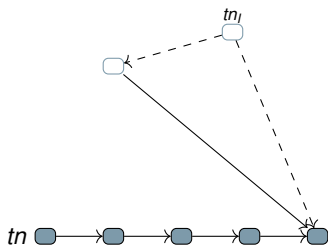
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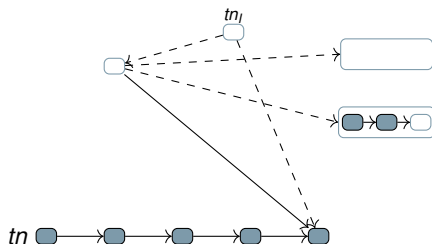
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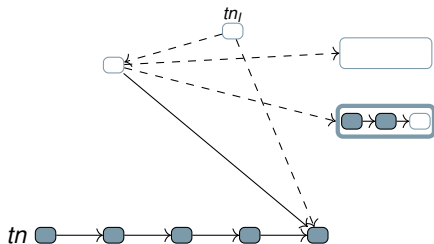
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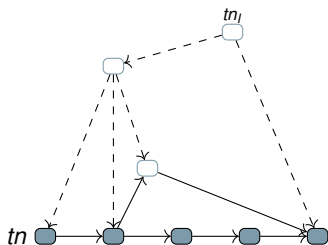
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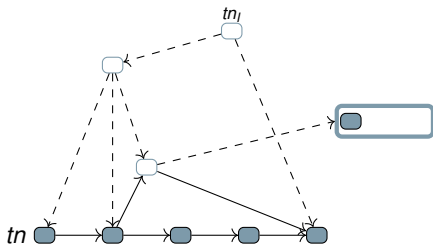
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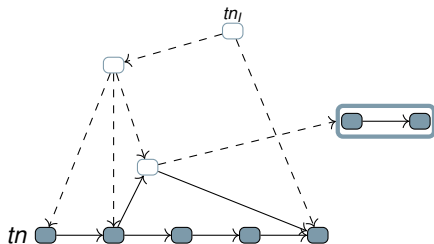
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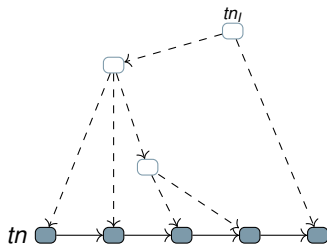
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Given Only an Action Sequence: Membership

Theorem

FIX-METHS_X is in NP.

Proof.

Key Observation: If there exists a sequence of changes that turns tn into a solution, then there must be one of length bounded by a polynomial.

- A totally-ordered HTN planning can be regarded as a CFG.
- Parsing based plan verification algorithms.



Given Only an Action Sequence

Theorem

FIX-METHS_X is NP-hard.

Proof.

- Reducing from the independent set problem.



Given an Action Sequence & a Method Sequence: Problem Definition

Definition (FIX-SEQ_X)

Given a planning problem P , a task network tn , and a method sequence \bar{m} . Is there a way to change the methods in P by using the allowed changes specified by X (e.g., ADD and DEL) such that \bar{m} decomposes the initial task network of P into tn .

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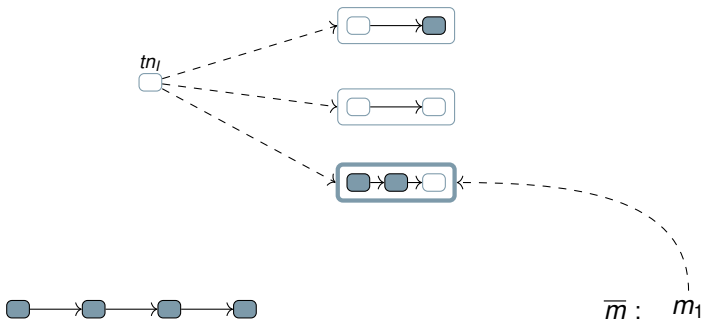
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 tn_I
 $\bar{m} :$

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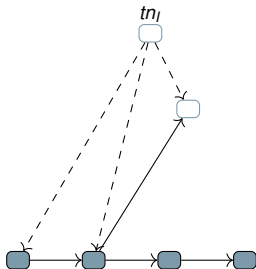
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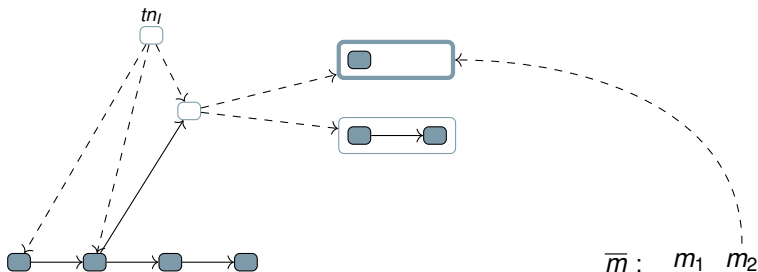
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 $\bar{m} : m_1$

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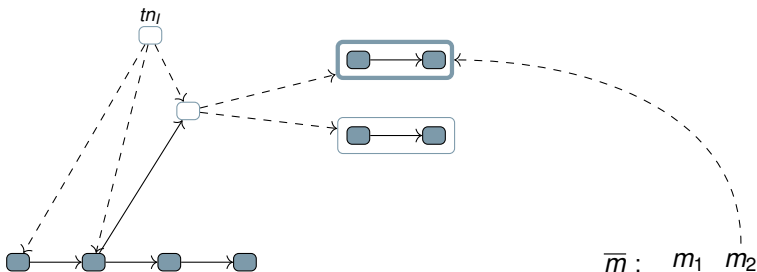
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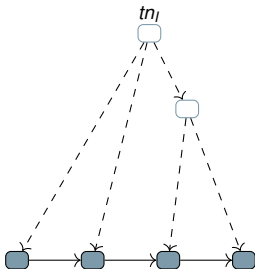
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 $\bar{m} : m_1 m_2$

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Theorem

FIX-SEQ_X is *NP-complete*.

Proof.

- Reduction from the independent set problem again.



Optimization: Finding the Minimal Number of Changes

Definition (FIX-METHS_X^k & FIX-SEQ_X^k)

Given an integer k , the problems FIX-METHS_X^k and FIX-SEQ_X^k are identical to FIX-METHS_X and FIX-SEQ_X except that we bounded the number of changes by k .

Corollary

FIX-METHS_X^k and FIX-SEQ_X^k are NP-complete.

Conclusion

Summary

Changes	Complexity
<i>prec</i> <i>del</i> <i>prec, del</i>	P
<i>add</i> <i>prec, add</i> <i>del, add</i> <i>prec, add, del</i>	NP-complete

Computational Complexity of Changing Actions.

Methods Given?	Changes	Complexity	
		Any Changes	k Changes
No	Del	NP-complete	NP-complete
	Add Add, Del		
Yes	All	NP-complete	NP-complete
Yes: Unique	All	P	P

Computational Complexity of Changing Methods.