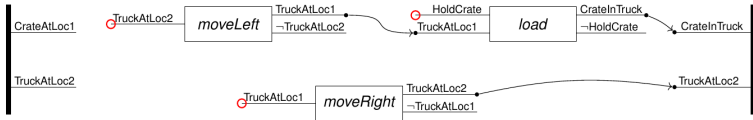
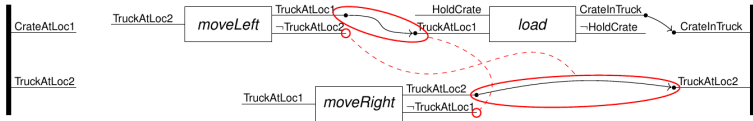


- **POCL plans:**



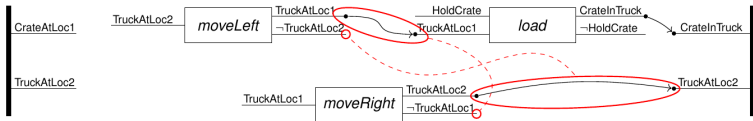
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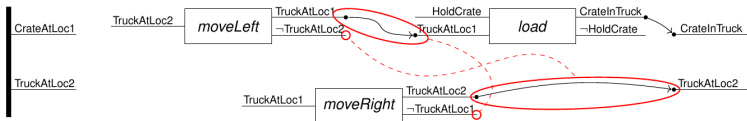
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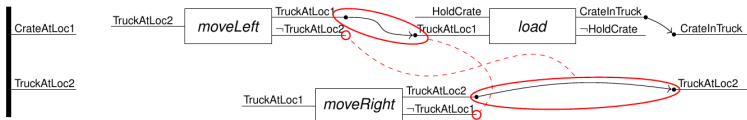
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- PO plans:**

- *They do not use causal links!* (The rest is the same.)
- A PO plan is a solution if:
 - every linearization is an executable action sequence.
 - (Verification does not use causal links, but follows similar ideas.)

Makespan := time to execute a plan by exploiting parallelism

- Are POCL plans equivalent to PO plans?

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- How hard is it to find a plan with better makespan by removing orderings? (answer: **NP-complete!**)