





Input:	A POCL plan $P$ .		
<b>Question:</b>	Can $P$ be refined into a solution?		
	(I.e., via the insertion of actions, links, and		

# A Closer Look at Causal Links: **Complexity Results for Delete-Relaxation** in Partial Order Causal Link (POCL) Planning

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rdering	insertable	Computational
nstraints	actions	Complexity
*	original	<b>PSPACE-complete</b>
tial order	delete-rel.	NP-complete
*	delete-rel.	in P
tal order	delete-rel.	in P
tial order	delete-rel.	NP-complete
tial order	none none	NP-complete in P

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