A Closer Look at Causal Links: Complexity Results for Delete-Relaxation in Partial Order Causal Link (POCL) Planning

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Motivation ••		

- Most planning systems generate action sequences as solutions!
- But plans may be just partially ordered in general.



• Here, causal links connect preconditions and effects.



Motivation ⊙●		
POCL Plans		

Why would we use POCL plans in the first place?

- In planning algorithms based on POCL plans:
  - Temporal planning due to parallelism
  - Some hierarchical approaches (some including time!)
  - For solving classical problems (not state of the art anymore)
- Some plan *encodings* (e.g., via SAT) rely on causal links.
  - To solve planning problems
  - For plan optimization



	Problem Formalization ●O	
POCL Plans		



• When is a POCL plan a solution?



	Problem Formalization ●O	
POCL Plans		



- When is a POCL plan a solution?
  - · When all preconditions are supported by a causal link, and



	Problem Formalization ●O	
POCL Plans		



- When is a POCL plan a solution?
  - · When all preconditions are supported by a causal link, and
  - there are no causal threats.
    Threats can be resolved by adding ordering constraints:



	Problem Formalization ●O	
POCL Plans		



- When is a POCL plan a solution?
  - When all preconditions are supported by a causal link, and
  - there are no causal threats.
    Threats can be resolved by adding ordering constraints:
    - Promotion: move c before a
    - Demotion: move c behind b



# Input: A POCL plan *P*. Question: Can *P* be refined into a solution? (I.e., via the insertion of actions, links, and orderings)

We study the computation complexity of deciding this question under various restrictions for P and the actions to be inserted!





Which problem relaxations could we perform?

(Delete-)relax the domain, i.e., the actions to insert.
 → Decidable in *P* for classical problems!



		Problem Relaxations ●○	
Relevant Problem	n Relaxations		

Which problem relaxations could we perform?

- (Delete-)relax the domain, i.e., the actions to insert.
  - $\rightarrow$  Decidable in *P* for classical problems!
- Relax the current plan/search node:
  - Delete-relax its actions



		Problem Relaxations ●○	
Relevant Problem	n Relaxations		

Which problem relaxations could we perform?

- (Delete-)relax the domain, i.e., the actions to insert.
  - $\rightarrow$  Decidable in *P* for classical problems!
- Relax the current plan/search node:
  - Delete-relax its actions
  - Ignore its causal links

Prize question: How to ignore existing causal links?

### Major contribution:

 $\rightarrow\,$  New problem relaxation that respects existing causal links despite delete relaxation!



		Problem Relaxations
Example for Res	pecting Causal Links	
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Additional actions:



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Where could these actions be inserted:

• A and middle: everywhere, since there are no conflicts.

a



### Example for Respecting Causal Links



Where could these actions be inserted:

- A and *middle*: everywhere, since there are no conflicts.
- *B1*: only before *middle*.



### Example for Respecting Causal Links



Where could these actions be inserted:

- A and middle: everywhere, since there are no conflicts.
- B1: only before middle.
- B2: only after middle.





 Input plan: partially ordered, delete-relaxed effects, causal links respected by inserted actions
 Insertable actions: delete-relaxed
 Complexity: NP-complete



		Complexity Results ●
Selection	of Results	

- Input plan: partially ordered, delete-relaxed effects, causal links respected by inserted actions
   Insertable actions: delete-relaxed
   Complexity: NP-complete
- Input plan: partially ordered, unchanged effects
  Insertable actions: delete-relaxed
  Complexity: NP-complete



		Complexity Results ●
Selection of	of Results	

- Input plan: partially ordered, delete-relaxed effects, causal links respected by inserted actions
   Insertable actions: delete-relaxed
   Complexity: NP-complete
- Input plan: partially ordered, unchanged effects
  Insertable actions: delete-relaxed
  Complexity: NP-complete

Want to see the proofs?  $\rightarrow$  See you at the poster! :)

